

512MB Registered DDR SDRAM DIMM

EBD51RC4AKFA-E (64M words × 72 bits, 1 Rank)

Description

The EBD51RC4AKFA is a 64M words × 72 bits, 1 rank Double Data Rate (DDR) SDRAM Module, mounting 18 pieces of DDR SDRAM sealed in TSOP package. Read and write operations are performed at the cross points of the CK and the /CK. This high-speed data transfer is realized by the 2-bit prefetch-pipelined architecture. Data strobe (DQS) both for read and write are available for high speed and reliable data bus design. By setting extended mode register, the on-chip Delay Locked Loop (DLL) can be set enable or disable. This module provides high density mounting without utilizing surface mount technology. Decoupling capacitors are mounted beside each TSOP on the module board.

Features

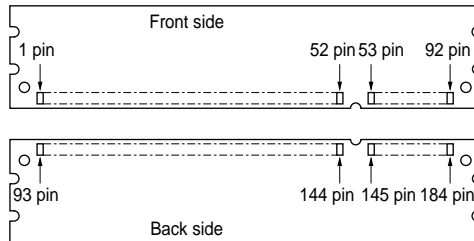
- 184-pin socket type dual in line memory module (DIMM)
 - PCB height: 30.48mm
 - Lead pitch: 1.27mm
 - Lead-free
- 2.5V power supply
- Data rate: 333Mbps/266Mbps (max.)
- 2.5 V (SSTL_2 compatible) I/O
- Double Data Rate architecture; two data transfers per clock cycle
- Bi-directional, data strobe (DQS) is transmitted /received with data, to be used in capturing data at the receiver
- Data inputs and outputs are synchronized with DQS
- 4 internal banks for concurrent operation (Components)
- DQS is edge aligned with data for READs; center aligned with data for WRITEs
- Differential clock inputs (CK and /CK)
- DLL aligns DQ and DQS transitions with CK transitions
- Commands entered on each positive CK edge; data referenced to both edges of DQS
- Auto precharge option for each burst access
- Programmable burst length: 2, 4, 8
- Programmable /CAS latency (CL): 2, 2.5
- Refresh cycles: (8192 refresh cycles /64ms)
 - 7.8μs maximum average periodic refresh interval
- 2 variations of refresh
 - Auto refresh
 - Self refresh
- 1 piece of PLL clock driver, 2 pieces of register drivers and 1 piece of serial EEPROM (2k bits EEPROM) for Presence Detect (PD)

Ordering Information

Part number	Data rate Mbps (max.)	Component JEDEC speed bin* ¹ (CL-tRCD-tRP)	Package	Contact pad	Mounted devices
EBD51RC4AKFA-6B-E	333	DDR333B (2.5-3-3)	184-pin DIMM	Gold	EDD2504AKTA-6B-E
EBD51RC4AKFA-7A-E	266	DDR266A (2-3-3)	(lead-free)		EDD2504AKTA-6B/7A-E
EBD51RC4AKFA-7B-E		DDR266B (2.5-3-3)			EDD2504AKTA-6B/7A/7B-E

Note: 1. Module /CAS latency = component CL + 1.

Pin Configurations



Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name
1	VREF	47	DQS8	93	VSS	139	VSS
2	DQ0	48	A0	94	DQ4	140	DM8/DQS17
3	VSS	49	CB2	95	DQ5	141	A10
4	DQ1	50	VSS	96	VDD	142	CB6
5	DQS0	51	CB3	97	DM0/DQS9	143	VDD
6	DQ2	52	BA1	98	DQ6	144	CB7
7	VDD	53	DQ32	99	DQ7	145	VSS
8	DQ3	54	VDD	100	VSS	146	DQ36
9	NC	55	DQ33	101	NC	147	DQ37
10	/RESET	56	DQS4	102	NC	148	VDD
11	VSS	57	DQ34	103	NC	149	DM4/DQS13
12	DQ8	58	VSS	104	VDD	150	DQ38
13	DQ9	59	BA0	105	DQ12	151	DQ39
14	DQS1	60	DQ35	106	DQ13	152	VSS
15	VDD	61	DQ40	107	DM1/DQS10	153	DQ44
16	NC	62	VDD	108	VDD	154	/RAS
17	NC	63	/WE	109	DQ14	155	DQ45
18	VSS	64	DQ41	110	DQ15	156	VDD
19	DQ10	65	/CAS	111	NC	157	/CS0
20	DQ11	66	VSS	112	VDD	158	NC
21	CKE0	67	DQS5	113	NC	159	DM5/DQS14
22	VDD	68	DQ42	114	DQ20	160	VSS
23	DQ16	69	DQ43	115	A12	161	DQ46
24	DQ17	70	VDD	116	VSS	162	DQ47
25	DQS2	71	NC	117	DQ21	163	NC
26	VSS	72	DQ48	118	A11	164	VDD
27	A9	73	DQ49	119	DM2/DQS11	165	DQ52

Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name	Pin No.	Pin name
28	DQ18	74	VSS	120	VDD	166	DQ53
29	A7	75	NC	121	DQ22	167	NC
30	VDD	76	NC	122	A8	168	VDD
31	DQ19	77	VDD	123	DQ23	169	DM6/DQS15
32	A5	78	DQS6	124	VSS	170	DQ54
33	DQ24	79	DQ50	125	A6	171	DQ55
34	VSS	80	DQ51	126	DQ28	172	VDD
35	DQ25	81	VSS	127	DQ29	173	NC
36	DQS3	82	VDDID	128	VDD	174	DQ60
37	A4	83	DQ56	129	DM3/DQS12	175	DQ61
38	VDD	84	DQ57	130	A3	176	VSS
39	DQ26	85	VDD	131	DQ30	177	DM7/DQS16
40	DQ27	86	DQS7	132	VSS	178	DQ62
41	A2	87	DQ58	133	DQ31	179	DQ63
42	VSS	88	DQ59	134	CB4	180	VDD
43	A1	89	VSS	135	CB5	181	SA0
44	CB0	90	NC	136	VDD	182	SA1
45	CB1	91	SDA	137	CK0	183	SA2
46	VDD	92	SCL	138	/CK0	184	VDDSPD

Pin Description

Pin name	Function
A0 to A12	Address input Row address A0 to A12 Column address A0 to A9, A11
BA0, BA1	Bank select address
DQ0 to DQ63	Data input/output
CB0 to CB7	Check bit (Data input/output)
/RAS	Row address strobe command
/CAS	Column address strobe command
/WE	Write enable
/CS0	Chip select
CKE0	Clock enable
CK0	Clock input
/CK0	Differential clock input
DQS0 to DQS8	Input and output data strobe
DM0 to DM8/DQS9 to DQS17	Input and output data strobe
SCL	Clock input for serial PD
SDA	Data input/output for serial PD
SA0 to SA2	Serial address input
VDD	Power for internal circuit
VDDSPD	Power for serial EEPROM
VREF	Input reference voltage
VSS	Ground
VDDID	VDD identification flag
/RESET	Reset pin (forces register inputs low)
NC	No connection

Serial PD Matrix*1

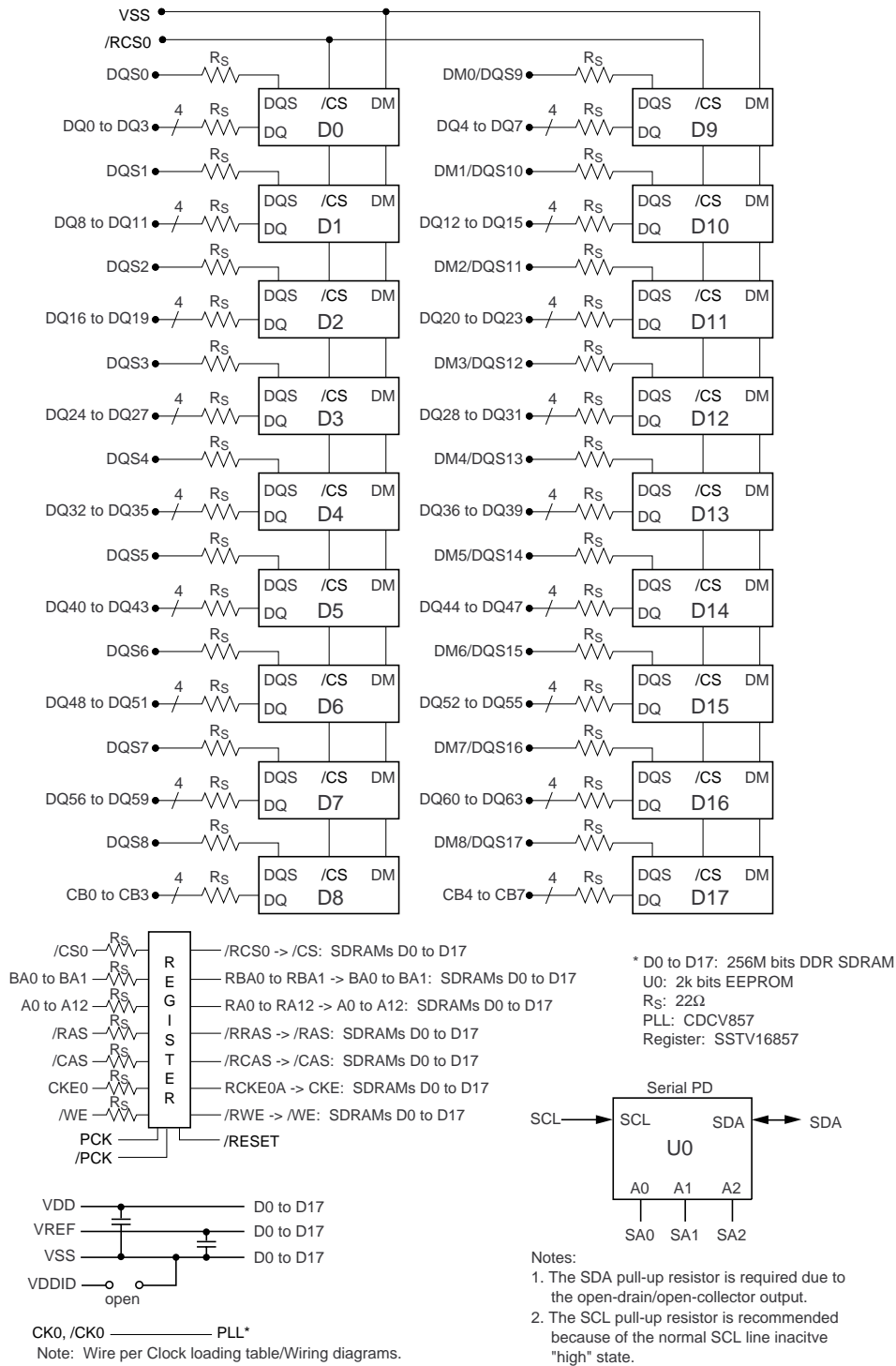
Byte No.	Function described	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	Hex value	Comments
0	Number of bytes utilized by module manufacturer	1	0	0	0	0	0	0	0	80H	128
1	Total number of bytes in serial PD device	0	0	0	0	1	0	0	0	08H	256 byte
2	Memory type	0	0	0	0	0	1	1	1	07H	SDRAM DDR
3	Number of row address	0	0	0	0	1	1	0	1	0DH	13
4	Number of column address	0	0	0	0	1	0	1	1	0BH	11
5	Number of DIMM ranks	0	0	0	0	0	0	0	1	01H	1
6	Module data width	0	1	0	0	1	0	0	0	48H	72 bits
7	Module data width continuation	0	0	0	0	0	0	0	0	00H	0 (+)
8	Voltage interface level of this assembly	0	0	0	0	0	1	0	0	04H	SSTL 2.5V
9	DDR SDRAM cycle time, CL = X -6B	0	1	1	0	0	0	0	0	60H	CL = 2.5*3
	-7A, -7B	0	1	1	1	0	1	0	1	75H	
10	SDRAM access from clock (tAC) -6B	0	1	1	1	0	0	0	0	70H	0.70ns*3
	-7A, -7B	0	1	1	1	0	1	0	1	75H	0.75ns*3
11	DIMM configuration type	0	0	0	0	0	0	1	0	02H	ECC
12	Refresh rate/type	1	0	0	0	0	0	1	0	82H	7.8 μs Self refresh
13	Primary SDRAM width	0	0	0	0	0	1	0	0	04H	× 4
14	Error checking SDRAM width	0	0	0	0	0	1	0	0	04H	× 4
15	SDRAM device attributes: Minimum clock delay back-to-back column access	0	0	0	0	0	0	0	1	01H	1 CLK
16	SDRAM device attributes: Burst length supported	0	0	0	0	1	1	1	0	0EH	2, 4, 8
17	SDRAM device attributes: Number of banks on SDRAM device	0	0	0	0	0	1	0	0	04H	4
18	SDRAM device attributes: /CAS latency	0	0	0	0	1	1	0	0	0CH	2, 2.5
19	SDRAM device attributes: /CS latency	0	0	0	0	0	0	0	1	01H	0
20	SDRAM device attributes: /WE latency	0	0	0	0	0	0	1	0	02H	1
21	SDRAM module attributes	0	0	1	0	0	1	1	0	26H	Registered
22	SDRAM device attributes: General	1	1	0	0	0	0	0	0	C0H	± 0.2V
23	Minimum clock cycle time at CLX - 0.5 -6B, -7A	0	1	1	1	0	1	0	1	75H	CL = 2*3
	-7B	1	0	1	0	0	0	0	0	A0H	
24	Maximum data access time (tAC) from clock at CLX - 0.5 -6B	0	1	1	1	0	0	0	0	70H	0.70ns*3
	-7A, -7B	0	1	1	1	0	1	0	1	75H	0.75ns*3
25	Minimum clock cycle time at CLX - 1	0	0	0	0	0	0	0	0	00H	
26	Maximum data access time (tAC) from clock at CLX - 1	0	0	0	0	0	0	0	0	00H	
27	Minimum row precharge time (tRP) -6B	0	1	0	0	1	0	0	0	48H	18ns
	-7A, -7B	0	1	0	1	0	0	0	0	50H	20ns

Byte No.	Function described	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	Hex value	Comments
28	Minimum row active to row active delay (tRRD) -6B	0	0	1	1	0	0	0	0	30H	12ns
	-7A, -7B	0	0	1	1	1	1	0	0	3CH	15ns
29	Minimum /RAS to /CAS delay (tRCD) -6B	0	1	0	0	1	0	0	0	48H	18ns
	-7A, -7B	0	1	0	1	0	0	0	0	50H	20ns
30	Minimum active to precharge time (tRAS) -6B	0	0	1	0	1	0	1	0	2AH	42ns
	-7A, -7B	0	0	1	0	1	1	0	1	2DH	45ns
31	Module rank density	1	0	0	0	0	0	0	0	80H	1 rank 512MB
32	Address and command setup time before clock (tIS) -6B	0	1	1	1	0	1	0	1	75H	0.75ns ^{*3}
	-7A, -7B	1	0	0	1	0	0	0	0	90H	0.9ns ^{*3}
33	Address and command hold time after clock (tIH) -6B	0	1	1	1	0	1	0	1	75H	0.75ns ^{*3}
	-7A, -7B	1	0	0	1	0	0	0	0	90H	0.9ns ^{*3}
34	Data input setup time before clock (tDS) -6B	0	1	0	0	0	1	0	1	45H	0.45ns ^{*3}
	-7A, -7B	0	1	0	1	0	0	0	0	50H	0.5ns ^{*3}
35	Data input hold time after clock (tDH) -6B	0	1	0	0	0	1	0	1	45H	0.45ns ^{*3}
	-7A, -7B	0	1	0	1	0	0	0	0	50H	0.5ns ^{*3}
36 to 40	Superset information	0	0	0	0	0	0	0	0	00H	Future use
41	Active command period (tRC) -6B	0	0	1	1	1	1	0	0	3CH	60ns ^{*3}
	-7A, -7B	0	1	0	0	0	0	0	1	41H	65ns ^{*3}
42	Auto refresh to active/ Auto refresh command cycle (tRFC) -6B	0	1	0	0	1	0	0	0	48H	72ns ^{*3}
	-7A, -7B	0	1	0	0	1	0	1	1	4BH	75ns ^{*3}
43	SDRAM tCK cycle max. (tCK max.)	0	0	1	1	0	0	0	0	30H	12ns ^{*3}
44	Dout to DQS skew -6B	0	0	1	0	1	1	0	1	2DH	0.45ns ^{*3}
	-7A, -7B	0	0	1	1	0	0	1	0	32H	0.5ns ^{*3}
45	Data hold skew (tQHS) -6B	0	1	0	1	0	1	0	1	55H	0.55ns ^{*3}
	-7A, -7B	0	1	1	1	0	1	0	1	75H	0.75ns ^{*3}
46 to 61	Superset information	0	0	0	0	0	0	0	0	00H	Future use
62	SPD revision	0	0	0	0	0	0	0	0	00H	Initial
63	Checksum for bytes 0 to 62 -6B	0	1	0	1	0	0	0	1	51H	81
	-7A	0	0	0	0	1	0	0	0	08H	8
	-7B	0	0	1	1	0	0	1	1	33H	51
64 to 65	Manufacturer's JEDEC ID code	0	1	1	1	1	1	1	1	7FH	Continuation code
66	Manufacturer's JEDEC ID code	1	1	1	1	1	1	1	0	FEH	Elpida Memory

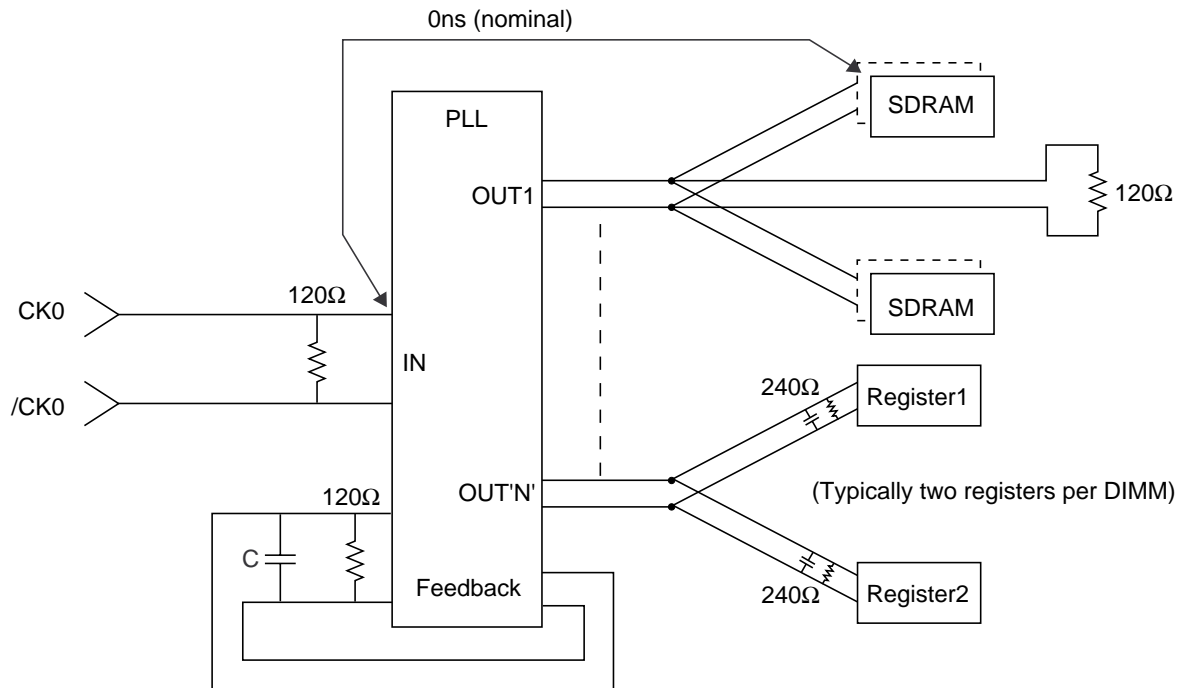
Byte No.	Function described	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	Hex value	Comments
67 to 71	Manufacturer's JEDEC ID code	0	0	0	0	0	0	0	0	00H	
72	Manufacturing location	×	×	×	×	×	×	×	×	×	*2 (ASCII-8bit code)
73	Module part number	0	1	0	0	0	1	0	1	45H	E
74	Module part number	0	1	0	0	0	0	1	0	42H	B
75	Module part number	0	1	0	0	0	1	0	0	44H	D
76	Module part number	0	0	1	1	0	1	0	1	35H	5
77	Module part number	0	0	1	1	0	0	0	1	31H	1
78	Module part number	0	1	0	1	0	0	1	0	52H	R
79	Module part number	0	1	0	0	0	0	1	1	43H	C
80	Module part number	0	0	1	1	0	1	0	0	34H	4
81	Module part number	0	1	0	0	0	0	0	1	41H	A
82	Module part number	0	1	0	0	1	0	1	1	4BH	K
83	Module part number	0	1	0	0	0	1	1	0	46H	F
84	Module part number	0	1	0	0	0	0	0	1	41H	A
85	Module part number	0	0	1	0	1	1	0	1	2DH	—
86	Module part number -6B	0	0	1	1	0	1	1	0	36H	6
	-7A, -7B	0	0	1	1	0	1	1	1	37H	7
87	Module part number -7A	0	1	0	0	0	0	0	1	41H	A
	-6B, -7B	0	1	0	0	0	0	1	0	42H	B
88	Module part number	0	0	1	0	1	1	0	1	2DH	—
89	Module part number	0	1	0	0	0	1	0	1	45H	E
90	Module part number	0	0	1	0	0	0	0	0	20H	(Space)
91	Revision code	0	0	1	1	0	0	0	0	30H	Initial
92	Revision code	0	0	1	0	0	0	0	0	20H	(Space)
93	Manufacturing date	×	×	×	×	×	×	×	×	×	Year code (HEX)
94	Manufacturing date	×	×	×	×	×	×	×	×	×	Week code (HEX)
95 to 98	Module serial number	*2									
99 to 127	Manufacturer specific data										

- Notes: 1. All serial PD data are not protected. 0: Serial data, "driven Low", 1: Serial data, "driven High"
2. Bytes 95 through 98 are assembly serial number.
3. These specifications are defined based on component specification, not module.

Block Diagram



Differential Clock Net Wiring (CK0, /CK0)



- Notes:
1. The clock delay from the input of the PLL clock to the input of any SDRAM or register will be set to 0 ns (nominal).
 2. Input, output and feedback clock lines are terminated from line to line as shown, and not from line to ground.
 3. Only one PLL output is shown per output type. Any additional PLL outputs will be wired in a similar manner.
 4. Termination resistors for feedback path clocks are located after the pins of the PLL.

Electrical Specifications

- All voltages are referenced to VSS (GND).

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit	Note
Voltage on any pin relative to VSS	VT	-1.0 to +3.6	V	
Supply voltage relative to VSS	VDD	-1.0 to +3.6	V	
Short circuit output current	IOS	50	mA	
Power dissipation	PD	18	W	
Operating ambient temperature	TA	0 to +70	°C	1
Storage temperature	Tstg	-55 to +125	°C	

Note: 1. DDR SDRAM component specification

Caution

Exposing the device to stress above those listed in Absolute Maximum Ratings could cause permanent damage. The device is not meant to be operated under conditions outside the limits described in the operational section of this specification. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

DC Operating Conditions (TA = 0 to +70°C) (DDR SDRAM Component Specification)

Parameter	Symbol	min.	typ.	max.	Unit	Notes
Supply voltage	VDD, VDDQ	2.3	2.5	2.7	V	1
	VSS	0	0	0	V	
Input reference voltage	VREF	$0.49 \times VDDQ$	$0.50 \times VDDQ$	$0.51 \times VDDQ$	V	
Termination voltage	VTT	$VREF - 0.04$	VREF	$VREF + 0.04$	V	
Input high voltage	VIH (DC)	$VREF + 0.15$	—	$VDDQ + 0.3$	V	2
Input low voltage	VIL (DC)	-0.3	—	$VREF - 0.15$	V	3
Input voltage level, CK and /CK inputs	VIN (DC)	-0.3	—	$VDDQ + 0.3$	V	4
Input differential cross point voltage, CK and /CK inputs	VIX (DC)	$0.5 \times VDDQ - 0.2V$	$0.5 \times VDDQ$	$0.5 \times VDDQ + 0.2V$	V	
Input differential voltage, CK and /CK inputs	VID (DC)	0.36	—	$VDDQ + 0.6$	V	5, 6

Notes: 1. VDDQ must be lower than or equal to VDD.

2. VIH is allowed to exceed VDD up to 3.6V for the period shorter than or equal to 5ns.

3. VIL is allowed to outreach below VSS down to -1.0V for the period shorter than or equal to 5ns.

4. VIN (DC) specifies the allowable DC execution of each differential input.

5. VID (DC) specifies the input differential voltage required for switching.

6. VIH (CK) min assumed over $VREF + 0.18V$, VIL (CK) max assumed under $VREF - 0.18V$ if measurement.

DC Characteristics 1 (TA = 0 to +70°C, VDD = 2.5V ± 0.2V, VSS = 0V)

Parameter	Symbol	Grade	max.	Unit	Test condition	Notes
Operating current (ACTV-PRE)	IDD0	-6B -7A, -7B	2190 2010	mA	CKE ≥ VIH, tRC = tRC (min.)	1, 2, 9
Operating current (ACTV-READ-PRE)	IDD1	-6B -7A, -7B	2640 2370	mA	CKE ≥ VIH, BL = 4, CL = 3.5, tRC = tRC (min.)	1, 2, 5
Idle power down standby current	IDD2P		444	mA	CKE ≤ VIL	4
Floating idle standby current	IDD2F	-6B -7A, -7B	840 750	mA	CKE ≥ VIH, /CS ≥ VIH, DQ, DQS, DM = VREF	4, 5
Quiet idle standby current	IDD2Q	-6B -7A, -7B	750 714	mA	CKE ≥ VIH, /CS ≥ VIH, DQ, DQS, DM = VREF	4, 10
Active power down standby current	IDD3P	-6B -7A, -7B	750 714	mA	CKE ≤ VIL	3
Active standby current	IDD3N	-6B -7A, -7B	1380 1290	mA	CKE ≥ VIH, /CS ≥ VIH tRAS = tRAS (max.)	3, 5, 6
Operating current (Burst read operation)	IDD4R	-6B -7A, -7B	3450 3090	mA	CKE ≥ VIH, BL = 2, CL = 3.5	1, 2, 5, 6
Operating current (Burst write operation)	IDD4W	-6B -7A, -7B	3630 3270	mA	CKE ≥ VIH, BL = 2, CL = 3.5	1, 2, 5, 6
Auto refresh current	IDD5	-6B -7A, -7B	3450 3360	mA	tRFC = tRFC (min.), Input ≤ VIL or ≥ VIH	
Self refresh current	IDD6		444	mA	Input ≥ VDD – 0.2 V Input ≤ 0.2 V	
Operating current (4 banks interleaving)	IDD7A	-6B -7A, -7B	6150 5250	mA	BL = 4	1, 5, 6, 7

- Notes. 1. These IDD data are measured under condition that DQ pins are not connected.
 2. One bank operation.
 3. One bank active.
 4. All banks idle.
 5. Command/Address transition once per one cycle.
 6. DQ, DM and DQS transition twice per one cycle.
 7. 4 banks active. Only one bank is running at tRC = tRC (min.)
 8. The IDD data on this table are measured with regard to tCK = tCK (min.) in general.
 9. Command/Address transition once every two clock cycles.
 10. Command/Address stable at ≥ VIH or ≤ VIL.

DC Characteristics 2 (TA = 0 to +70°C, VDD, VDDQ = 2.5V ± 0.2V, VSS = 0V)

(DDR SDRAM component Specification)

Parameter	Symbol	min.	max.	Unit	Test condition	Note
Input leakage current	ILI	-2	2	μA	VDD ≥ VIN ≥ VSS	
Output leakage current	ILO	-5	5	μA	VDDQ ≥ VOUT ≥ VSS	
Output high current	IOH	-15.2	—	mA	VOUT = 1.95V	
Output low current	IOL	15.2	—	mA	VOUT = 0.35V	

Pin Capacitance (TA = 25°C, VDD = 2.5V ± 0.2V)

Parameter	Symbol	Pins	max.	Unit	Notes
Input capacitance	CI1	Address, /RAS, /CAS, /WE, /CS, CKE	15	pF	1, 3
Input capacitance	CI2	CK, /CK	20	pF	1, 3
Data and DQS input/output capacitance	CO	DQ, DQS, CB	15	pF	1, 2, 3

- Notes: 1. These parameters are measured on conditions: f = 100MHz, VOUT = VDDQ/2, ΔVOUT = 0.2V.
 2. Dout circuits are disabled.
 3. This parameter is sampled and not 100% tested.

AC Characteristics (TA = 0 to +70°C, VDD, VDDQ = 2.5V ± 0.2V, VSS = 0V)

(DDR SDRAM component Specification)

Parameter	Symbol	-6B		-7A		-7B		Unit	Notes
		min.	max.	min.	max.	min.	max.		
Clock cycle time (CL = 2)	tCK	7.5	12	7.5	12	10	12	ns	10
(CL = 2.5)	tCK	6	12	7.5	12	7.5	12	ns	
CK high-level width	tCH	0.45	0.55	0.45	0.55	0.45	0.55	tCK	
CK low-level width	tCL	0.45	0.55	0.45	0.55	0.45	0.55	tCK	
CK half period	tHP	min (tCH, tCL)	—	min (tCH, tCL)	—	min (tCH, tCL)	—	tCK	
DQ output access time from CK, /CK	tAC	-0.7	0.7	-0.75	0.75	-0.75	0.75	ns	2, 11
DQS output access time from CK, /CK	tDQACK	-0.6	0.6	-0.75	0.75	-0.75	0.75	ns	2, 11
DQS to DQ skew	tDQSQ	—	0.45	—	0.5	—	0.5	ns	3
DQ/DQS output hold time from DQS	tQH	tHP – tQHS	—	tHP – tQHS	—	tHP – tQHS	—	ns	
Data hold skew factor	tQHS	—	0.55	—	0.75	—	0.75	ns	
Data-out high-impedance time from CK, /CK	tHZ	-0.7	0.7	-0.75	0.75	-0.75	0.75	ns	5, 11
Data-out low-impedance time from CK, /CK	tLZ	-0.7	0.7	-0.75	0.75	-0.75	0.75	ns	6, 11
Read preamble	tRPRE	0.9	1.1	0.9	1.1	0.9	1.1	tCK	
Read postamble	tRPST	0.4	0.6	0.4	0.6	0.4	0.6	tCK	
DQ and DM input setup time	tDS	0.45	—	0.5	—	0.5	—	ns	8
DQ and DM input hold time	tDH	0.45	—	0.5	—	0.5	—	ns	8
DQ and DM input pulse width	tDIPW	1.75	—	1.75	—	1.75	—	ns	7
Write preamble setup time	tWPRES	0	—	0	—	0	—	ns	
Write preamble	tWPRE	0.25	—	0.25	—	0.25	—	tCK	
Write postamble	tWPST	0.4	0.6	0.4	0.6	0.4	0.6	tCK	9
Write command to first DQS latching transition	tDQSS	0.75	1.25	0.75	1.25	0.75	1.25	tCK	
DQS falling edge to CK setup time	tDSS	0.2	—	0.2	—	0.2	—	tCK	
DQS falling edge hold time from CK	tDSH	0.2	—	0.2	—	0.2	—	tCK	
DQS input high pulse width	tDQSH	0.35	—	0.35	—	0.35	—	tCK	
DQS input low pulse width	tDQSL	0.35	—	0.35	—	0.35	—	tCK	
Address and control input setup time	tIS	0.75	—	0.9	—	0.9	—	ns	8
Address and control input hold time	tIH	0.75	—	0.9	—	0.9	—	ns	8

Parameter	Symbol	-6B		-7A		-7B		Unit	Notes
		min.	max.	min.	max.	min.	max.		
Address and control input pulse width	tIPW	2.2	—	2.2	—	2.2	—	ns	7
Mode register set command cycle time	tMRD	2	—	2	—	2	—	tCK	
Active to Precharge command period	tRAS	42	120000	45	120000	45	120000	ns	
Active to Active/Auto refresh command period	tRC	60	—	65	—	65	—	ns	
Auto refresh to Active/Auto refresh command period	tRFC	72	—	75	—	75	—	ns	
Active to Read/Write delay	tRCD	18	—	20	—	20	—	ns	
Precharge to active command period	tRP	18	—	20	—	20	—	ns	
Active to auto precharge delay	tRAP	tRCD min.	—	tRCD min.	—	tRCD min.	—	ns	
Active to active command period	tRRD	12	—	15	—	15	—	ns	
Write recovery time	tWR	15	—	15	—	15	—	ns	
Auto precharge write recovery and precharge time	tDAL	(tWR/tCK)+ (tRP/tCK)	—	(tWR/tCK)+ (tRP/tCK)	—	(tWR/tCK)+ (tRP/tCK)	—	tCK	13
Internal write to Read command delay	tWTR	1	—	1	—	1	—	tCK	
Average periodic refresh interval	tREF	—	7.8	—	7.8	—	7.8	μs	

Notes: 1. All the AC parameters listed in this data sheet is component specifications. For AC testing conditions, refer to the corresponding component data sheet.

2. This parameter defines the signal transition delay from the cross point of CK and /CK. The signal transition is defined to occur when the signal level crossing VTT.
3. The timing reference level is VTT.
4. Output valid window is defined to be the period between two successive transition of data out or DQS (read) signals. The signal transition is defined to occur when the signal level crossing VTT.
5. tHZ is defined as DOUT transition delay from Low-Z to High-Z at the end of read burst operation. The timing reference is cross point of CK and /CK. This parameter is not referred to a specific DOUT voltage level, but specify when the device output stops driving.
6. tLZ is defined as DOUT transition delay from High-Z to Low-Z at the beginning of read operation. This parameter is not referred to a specific DOUT voltage level, but specify when the device output begins driving.
7. Input valid windows is defined to be the period between two successive transition of data input or DQS (write) signals. The signal transition is defined to occur when the signal level crossing VREF.
8. The timing reference level is VREF.
9. The transition from Low-Z to High-Z is defined to occur when the device output stops driving. A specific reference voltage to judge this transition is not given.
10. tCK (max.) is determined by the lock range of the DLL. Beyond this lock range, the DLL operation is not assured.
11. tCK = tCK (min.) when these parameters are measured. Otherwise, absolute minimum values of these values are 10% of tCK.
12. VDD is assumed to be 2.5V ± 0.2V. VDD power supply variation per cycle expected to be less than 0.4V/400 cycle.
13. tDAL = (tWR/tCK)+(tRP/tCK)

For each of the terms above, if not already an integer, round to the next highest integer.

Example: For -7A Speed at CL = 2.5, tCK = 7.5ns, tWR = 15ns and tRP= 20ns,

$$tDAL = (15ns/7.5ns) + (20ns/7.5ns) = (2) + (3)$$

$$tDAL = 5 \text{ clocks}$$

Timing Parameter Measured in Clock Cycle for Registered DIMM

tCK	Parameter	Symbol	Number of clock cycle				Unit
			6ns		7.5ns		
			min.	max.	min.	max.	
	Write to pre-charge command delay (same bank)	tWPD	4 + BL/2	—	3 + BL/2	—	tCK
	Read to pre-charge command delay (same bank)	tRPD	BL/2	—	BL/2	—	tCK
	Write to read command delay (to input all data)	tWRD	2 + BL/2	—	2 + BL/2	—	tCK
	Burst stop command to write command delay (CL = 3)	tBSTW	—	—	2	—	tCK
	(CL = 3.5)	tBSTW	3	—	3	—	tCK
	Burst stop command to DQ High-Z (CL = 3)	tBSTZ	—	—	3	3	tCK
	(CL = 3.5)	tBSTZ	3.5	3.5	3.5	3.5	tCK
	Read command to write command delay (to output all data) (CL = 3)	tRWD	—	—	2 + BL/2	—	tCK
	(CL = 3.5)	tRWD	3 + BL/2	—	3 + BL/2	—	tCK
	Pre-charge command to High-Z (CL = 3)	tHZP	—	—	3	3	tCK
	(CL = 3.5)	tHZP	3.5	3.5	3.5	3.5	tCK
	Write command to data in latency	tWCD	2	2	2	2	tCK
	Write recovery	tWR	2	—	1	—	tCK
	Register set command to active or register set command	tMRD	2	—	2	—	tCK
	Self refresh exit to non-read command	tSNR	12	—	10	—	tCK
	Self refresh exit to read command	tSRD	200	—	200	—	tCK
	Power down entry	tPDEN	1	1	1	1	tCK
	Power down exit to command input	tPDEX	1	—	1	—	tCK

Pin Functions

CK, /CK (input pin)

The CK and the /CK are the master clock inputs. All inputs except DMs, DQSs and DQs are referred to the cross point of the CK rising edge and the VREF level. When a read operation, DQSs and DQs are referred to the cross point of the CK and the /CK. When a write operation, DMs and DQs are referred to the cross point of the DQS and the VREF level. DQSs for write operation are referred to the cross point of the CK and the /CK.

/CS (input pin)

When /CS is low, commands and data can be input. When /CS is high, all inputs are ignored. However, internal operations (bank active, burst operations, etc.) are held.

/RAS, /CAS, and /WE (input pins)

These pins define operating commands (read, write, etc.) depending on the combinations of their voltage levels. See "Command operation".

A0 to A12 (input pins)

Row address (AX0 to AX12) is determined by the A0 to the A12 level at the cross point of the CK rising edge and the VREF level in a bank active command cycle. Column address (AY0 to AY9, AY11) is loaded via the A0 to the A9 and the A11 at the cross point of the CK rising edge and the VREF level in a read or a write command cycle. This column address becomes the starting address of a burst operation.

A10 (AP) (input pin)

A10 defines the precharge mode when a precharge command, a read command or a write command is issued. If A10 = high when a precharge command is issued, all banks are precharged. If A10 = low when a precharge command is issued, only the bank that is selected by BA1, BA0 is precharged. If A10 = high when read or write command, auto-precharge function is enabled. While A10 = low, auto-precharge function is disabled.

BA0, BA1 (input pin)

BA0, BA1 are bank select signals (BA). The memory array is divided into bank 0, bank 1, bank 2 and bank 3. (See Bank Select Signal Table)

[Bank Select Signal Table]

	BA0	BA1
Bank 0	L	L
Bank 1	H	L
Bank 2	L	H
Bank 3	H	H

Remark: H: VIH. L: VIL.

CKE (input pin)

CKE controls power down and self-refresh. The power down and the self-refresh commands are entered when the CKE is driven low and exited when it resumes to high.

The CKE level must be kept for 1 CK cycle at least, that is, if CKE changes at the cross point of the CK rising edge and the VREF level with proper setup time tIS, at the next CK rising edge CKE level must be kept with proper hold time tIH.

DQ, CB (input and output pins)

Data are input to and output from these pins.

DQS (input and output pin)

DQS provide the read data strobes (as output) and the write data strobes (as input).

VDD (power supply pins)

2.5V is applied. (VDD is for the internal circuit.)

VDDSPD (power supply pin)

2.5V is applied (For serial EEPROM).

VSS (power supply pin)

Ground is connected.

/RESET (input pin)

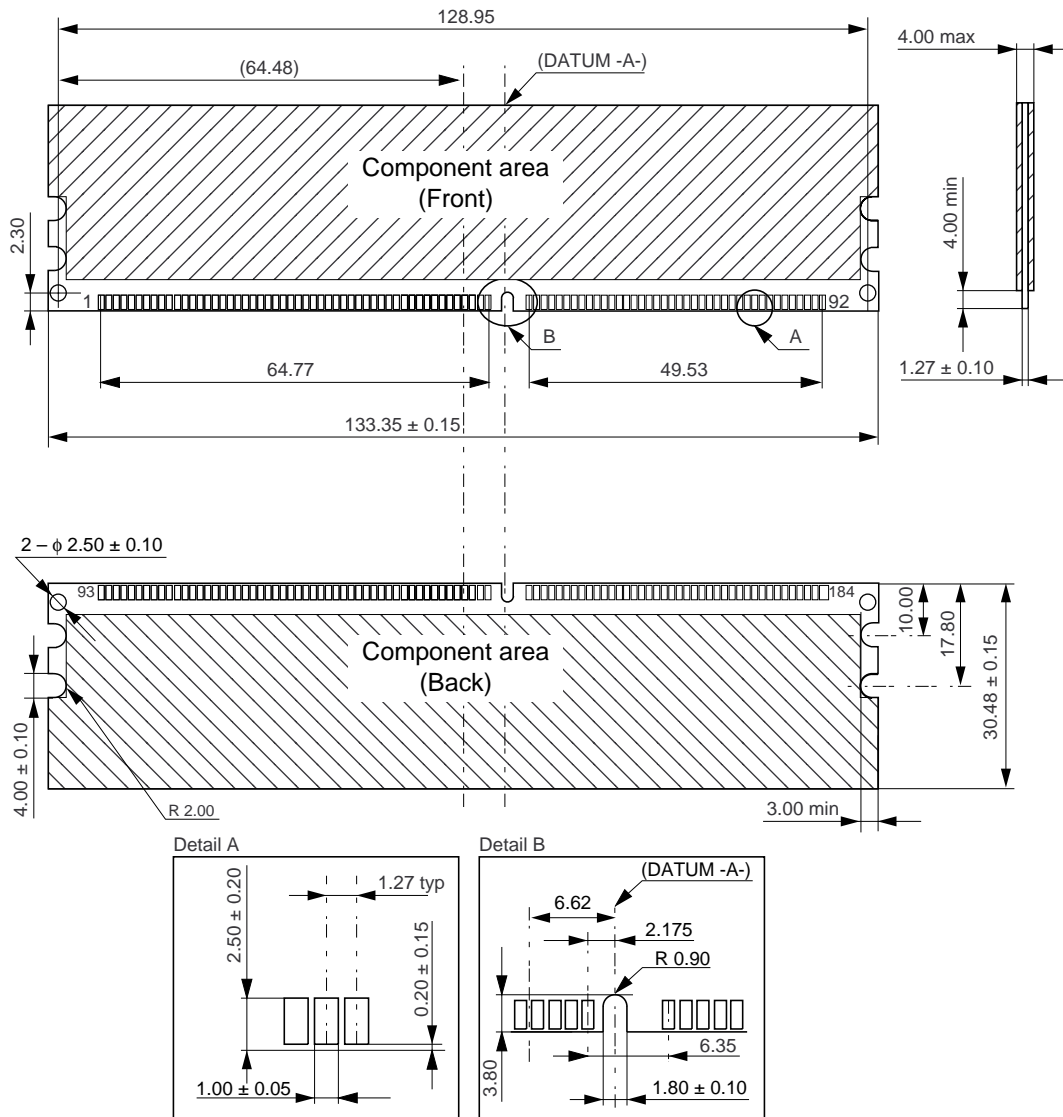
LVC MOS reset input. When /RESET is low, all registers are reset and all outputs are low.

Detailed Operation Part and Timing Waveforms

Refer to the EDD2504AKTA-E datasheet (E0610E). DM pins of component device fixed to VSS level on the module board. DIMM /CAS latency = component CL + 1 for registered type.

Physical Outline

Unit: mm



Note: Tolerance on all dimensions ± 0.13 unless otherwise specified.

ECA-TS2-0050-01

CAUTION FOR HANDLING MEMORY MODULES

When handling or inserting memory modules, be sure not to touch any components on the modules, such as the memory ICs, chip capacitors and chip resistors. It is necessary to avoid undue mechanical stress on these components to prevent damaging them.

In particular, do not push module cover or drop the modules in order to protect from mechanical defects, which would be electrical defects.

When re-packing memory modules, be sure the modules are not touching each other.

Modules in contact with other modules may cause excessive mechanical stress, which may damage the modules.

MDE0202

NOTES FOR CMOS DEVICES**① PRECAUTION AGAINST ESD FOR MOS DEVICES**

Exposing the MOS devices to a strong electric field can cause destruction of the gate oxide and ultimately degrade the MOS devices operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it, when once it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. MOS devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. MOS devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor MOS devices on it.

② HANDLING OF UNUSED INPUT PINS FOR CMOS DEVICES

No connection for CMOS devices input pins can be a cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to V_{DD} or GND with a resistor, if it is considered to have a possibility of being an output pin. The unused pins must be handled in accordance with the related specifications.

③ STATUS BEFORE INITIALIZATION OF MOS DEVICES

Power-on does not necessarily define initial status of MOS devices. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the MOS devices with reset function have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. MOS devices are not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for MOS devices having reset function.

CME0107

The information in this document is subject to change without notice. Before using this document, confirm that this is the latest version.

No part of this document may be copied or reproduced in any form or by any means without the prior written consent of Elpida Memory, Inc.

Elpida Memory, Inc. does not assume any liability for infringement of any intellectual property rights (including but not limited to patents, copyrights, and circuit layout licenses) of Elpida Memory, Inc. or third parties by or arising from the use of the products or information listed in this document. No license, express, implied or otherwise, is granted under any patents, copyrights or other intellectual property rights of Elpida Memory, Inc. or others.

Descriptions of circuits, software and other related information in this document are provided for illustrative purposes in semiconductor product operation and application examples. The incorporation of these circuits, software and information in the design of the customer's equipment shall be done under the full responsibility of the customer. Elpida Memory, Inc. assumes no responsibility for any losses incurred by customers or third parties arising from the use of these circuits, software and information.

[Product applications]

Elpida Memory, Inc. makes every attempt to ensure that its products are of high quality and reliability. However, users are instructed to contact Elpida Memory's sales office before using the product in aerospace, aeronautics, nuclear power, combustion control, transportation, traffic, safety equipment, medical equipment for life support, or other such application in which especially high quality and reliability is demanded or where its failure or malfunction may directly threaten human life or cause risk of bodily injury.

[Product usage]

Design your application so that the product is used within the ranges and conditions guaranteed by Elpida Memory, Inc., including the maximum ratings, operating supply voltage range, heat radiation characteristics, installation conditions and other related characteristics. Elpida Memory, Inc. bears no responsibility for failure or damage when the product is used beyond the guaranteed ranges and conditions. Even within the guaranteed ranges and conditions, consider normally foreseeable failure rates or failure modes in semiconductor devices and employ systemic measures such as fail-safes, so that the equipment incorporating Elpida Memory, Inc. products does not cause bodily injury, fire or other consequential damage due to the operation of the Elpida Memory, Inc. product.

[Usage environment]

This product is not designed to be resistant to electromagnetic waves or radiation. This product must be used in a non-condensing environment.

If you export the products or technology described in this document that are controlled by the Foreign Exchange and Foreign Trade Law of Japan, you must follow the necessary procedures in accordance with the relevant laws and regulations of Japan. Also, if you export products/technology controlled by U.S. export control regulations, or another country's export control laws or regulations, you must follow the necessary procedures in accordance with such laws or regulations.

If these products/technology are sold, leased, or transferred to a third party, or a third party is granted license to use these products, that third party must be made aware that they are responsible for compliance with the relevant laws and regulations.

M01E0107