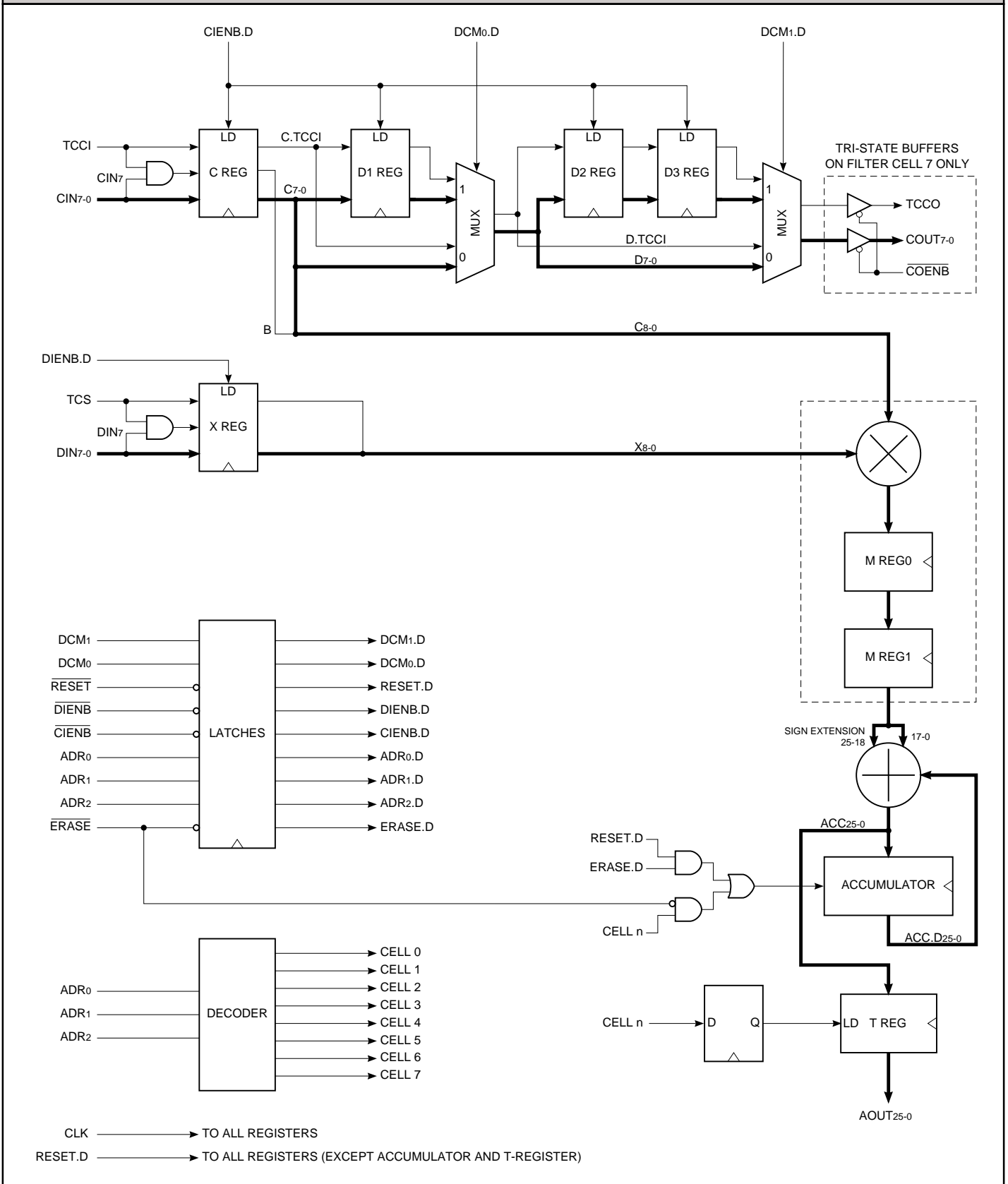




**FIGURE 1. FILTER CELL DIAGRAM**



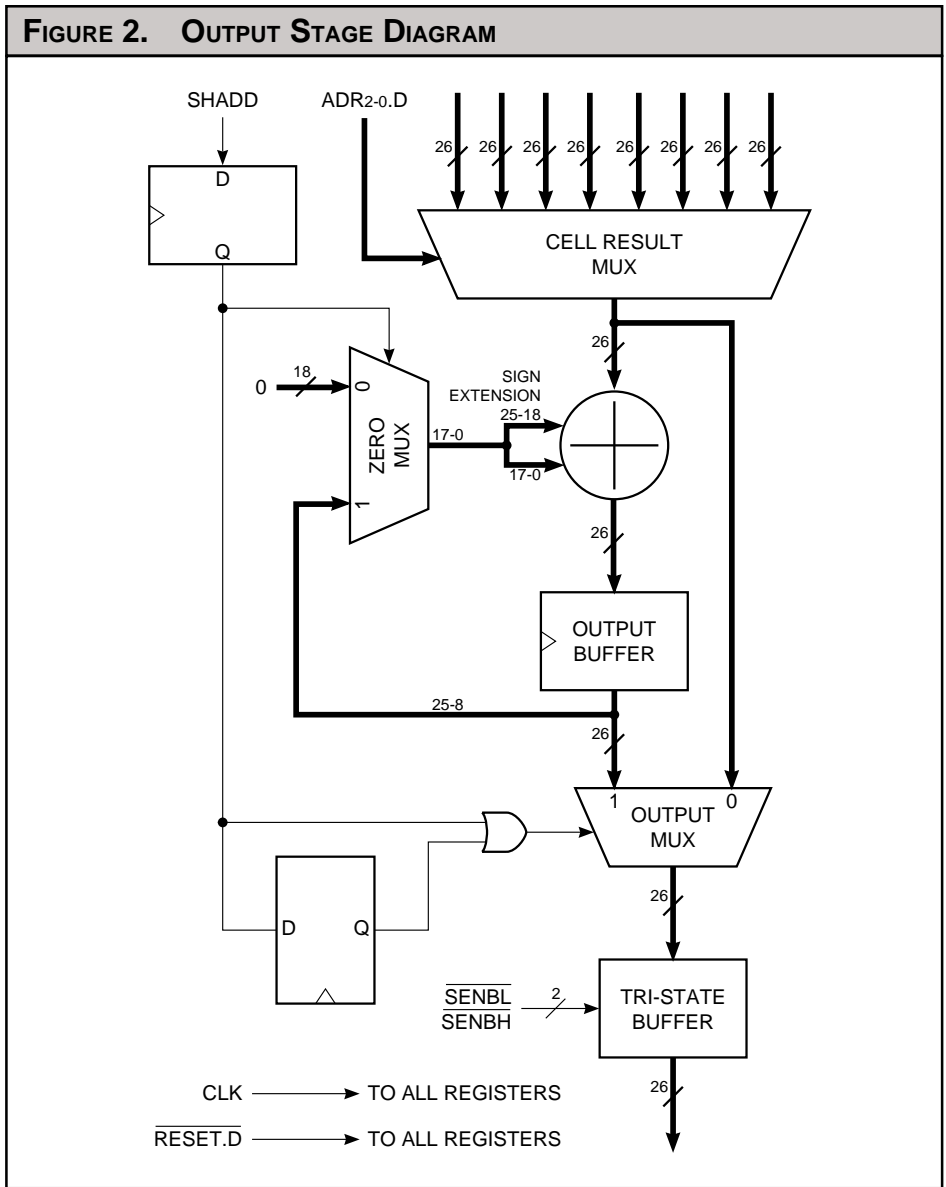
**FILTER CELL DESCRIPTION**

8-bit coefficients are loaded into the C register (CIN7-0) and are output as COUT7-0 (the COENB signal enables the COUT7-0 outputs). The path taken by the coefficients varies according to the decimation mode chosen. With no decimation, the coefficients move directly from the C register, bypassing all decimation registers, and are available at the output on the following clock cycle. When decimation is chosen, the coefficient output is delayed by 1, 2, or 3 clock cycles depending on how many decimation registers the coefficients pass through (D1, D2, or D3). The number of decimation registers the coefficients pass through is determined by DCM1-0. Refer to Table 1 for choosing a decimation mode.

$\overline{\text{CIENB}}$  enables the C and D registers for coefficient loading. The registers are loaded on the rising edge of CLK when  $\overline{\text{CIENB}}$  is LOW.  $\overline{\text{CIENB}}$  is latched and delayed internally which enables the registers for loading one clock cycle after  $\overline{\text{CIENB}}$  goes active (loading takes place on the second rising edge of CLK after  $\overline{\text{CIENB}}$  goes LOW). Therefore,  $\overline{\text{CIENB}}$  must be LOW one clock cycle before the coefficients are placed on the CIN7-0 inputs. The coefficients are held when  $\overline{\text{CIENB}}$  is HIGH.

$\overline{\text{DIENB}}$  enables the X register for the loading of data. The X register is loaded on the rising edge of CLK when  $\overline{\text{DIENB}}$  is LOW.  $\overline{\text{DIENB}}$  is latched and delayed internally (loading takes place on the second rising edge of CLK after  $\overline{\text{DIENB}}$  goes LOW). Therefore,  $\overline{\text{DIENB}}$  must be LOW one clock cycle before the data is placed on the DIN7-0 inputs. The X register is loaded with all zeros when  $\overline{\text{DIENB}}$  is HIGH.

The output of the C register (C8-0) and X register (X8-0) provide the inputs of the 8 x 8 multiplier. The multiplier is followed by two pipeline registers,



M REG0 and M REG1. The output of the multiplier is sign extended and is used as one of the inputs to the 26-bit adder. The output of the 26-bit accumulator provides the second input to the adder. Both the accumulator and T register are loaded simultaneously with the output of the adder.

The accumulator is loaded with the output of the adder on every clock cycle unless cleared. Clearing the accumulator can be achieved using two methods. The first method, when both  $\overline{\text{RESET}}$  and  $\overline{\text{ERASE}}$  are LOW, causes all accumulators and all

registers in the device to be cleared together.  $\overline{\text{RESET}}$  and  $\overline{\text{ERASE}}$  are latched and delayed internally causing the clearing to occur on the second clock cycle after  $\overline{\text{RESET}}$  and  $\overline{\text{ERASE}}$  go active.

The second method, when only  $\overline{\text{ERASE}}$  is LOW, clears a single accumulator of a selected cell. The cell is selected using the ADR2-0 inputs (decoded to Cell n).  $\overline{\text{ERASE}}$  is latched and delayed internally causing the clearing to occur on the second clock cycle after  $\overline{\text{ERASE}}$  goes active. Refer to Table 2 for clearing registers and accumulators.

TABLE 1. DECIMATION MODE SELECTION		
DCM1	DCM0	Decimation Function
0	0	Decimation registers not used
0	1	One decimation register used (decimation by one-half)
1	0	Two decimation registers used (decimation by one-third)
1	1	Three decimation registers used (decimation by one-fourth)

TABLE 2. REGISTER AND ACCUMULATOR CLEARING		
ERASE	RESET	Clearing Effect
0	0	All accumulators and all registers are cleared
0	1	Only the accumulator addressed by ADR2-0 is cleared
1	0	All registers are cleared (accumulators are not cleared)
1	1	No clearing occurs, internal state remains the same

**OUTPUT STAGE DESCRIPTION**

The 26-bit adder contained in the output stage can add the contents of any filter cell accumulator (selected by ADR2-0) with the 18 most significant bits of the output buffer. The result is stored back into the output buffer. The complete operation takes only one clock cycle. The eight least significant bits of the output buffer are lost.

The Zero multiplexer is controlled by the SHADD input signal. This allows selection of either the 18 most significant bits of the output buffer or all zeros for the adder input. When SHADD is LOW, all zeros will be selected. When SHADD is HIGH, the 18 most significant bits of the output buffer are selected enabling the shift-and-add operation. SHADD is latched and delayed internally by one clock cycle.

The output multiplexer is also controlled by the SHADD input signal. This allows selection of either a filter cell accumulator, selected by ADR2-0, or the output buffer to be output to the SUM25-0 bus. Only the 26 least significant bits from either a filter cell accumulator or the output buffer are output on SUM25-0. If SHADD is LOW during two consecutive clock cycles (low during the current and previous clock cycle), the output

multiplexer selects the contents of a filter cell accumulator addressed by ADR2-0. Otherwise, the output multiplexer selects the contents of the output buffer.

If the same address remains on the ADR2-0 inputs for more than one clock cycle, SUM25-0 will not change to reflect any updates to the addressed cell accumulator. Only the result from the first selection of the cell (first clock cycle) will be output. This allows the interface of slow memory devices where the output needs to be active for more than one clock cycle. Normal FIR operation is not affected because ADR2-0 is changed sequentially.

**NUMBER SYSTEMS**

Data and coefficients can be represented as either unsigned or two's complement numbers. The TCS and TCCI inputs determine which of the two formats is to be used. All values are represented as 9-bit two's complement numbers internally. The value of the ninth bit is determined by the number system selected. The ninth bit is a sign extended bit when the two's complement mode is chosen. When the unsigned mode is chosen, the ninth bit is zero.

**SIGNAL DEFINITIONS**

**Power**

*VCC and GND*

+5 V power supply. All pins must be connected.

**Clock**

*CLK — Master Clock*

The rising edge of CLK strobes all registers. All timing specifications are referenced to the rising edge of CLK.

**Inputs**

*DIN7-0 — Data Input*

8-bit data is latched into the X register of each filter cell simultaneously. The TCS signal selects the appropriate data format type. The DIENB signal enables loading of the data.

*CIN7-0 — Coefficient Input*

8-bit coefficients are latched into the C register of Filter Cell 0. The TCCI signal selects the appropriate coefficient format type. The CIENB signal enables loading of the coefficients.

**Outputs**

*SUM25-0 — Data Output*

The 26-bit result from an individual filter cell will appear when ADR2-0 is used to select the filter cell result. SHADD in conjunction with ADR2-0 is used to select the output from the shift-and-add output stage.

*COU7-0 — Coefficient Output*

The 8-bit coefficient output from Filter Cell 7 can be connected to the CIN7-0 coefficient input of the same LF43881 to recirculate the coefficients. COU7-0 can also be connected to the CIN7-0 of another LF43881 to cascade the devices. The COENB signal enables the output of the coefficients.

**Controls**

*TCS — Data Format Control*

The TCS input determines the interpretation of the input data. When TCS is HIGH, two's complement arithmetic is used. When TCS is LOW, unsigned arithmetic is used.

*TCCI — Coefficient Input Format Control*

The TCCI input determines the interpretation of the coefficients. When TCCI is HIGH, two's complement arithmetic is used. When TCCI is LOW, unsigned arithmetic is used.

*TCCO — Coefficient Output Format*

The TCCO output shows the format of the COUT7-0 coefficient output. TCCO follows the TCCI input. When cascading multiple LF43881s, the TCCO output of one device should be connected to the TCCI input of another device. The  $\overline{\text{COENB}}$  signal enables TCCO.

*$\overline{\text{DIENB}}$  — Data Input Enable*

The  $\overline{\text{DIENB}}$  input enables the X register of every filter cell. While  $\overline{\text{DIENB}}$  is LOW, the X registers are loaded with the data present at the DIN7-0 inputs on the rising edge of CLK. While  $\overline{\text{DIENB}}$  is HIGH, all bits of DIN7-0 are forced to zero and a rising edge of CLK will load the X register of every filter cell with all zeros.  $\overline{\text{DIENB}}$  must be low one clock cycle prior to presenting the input data on the DIN7-0 input since it is latched and delayed internally.

*$\overline{\text{CIENB}}$  — Coefficient Input Enable*

The  $\overline{\text{CIENB}}$  input enables the C and D registers of every filter cell. While  $\overline{\text{CIENB}}$  is LOW, the C and appropriate D registers are loaded with the coefficient data on the rising edge of CLK. While  $\overline{\text{CIENB}}$  is HIGH, the contents of the C and D registers are held and the CLK signal is ignored. By using  $\overline{\text{CIENB}}$  in its active state, coefficient data can be shifted from cell to cell.  $\overline{\text{CIENB}}$  must be low one clock cycle prior to presenting the coefficient data on the CIN7-0 input since it is latched and delayed internally.

*$\overline{\text{COENB}}$  — Coefficient Output Enable*

The  $\overline{\text{COENB}}$  input enables the COUT7-0 and TCCO outputs. When  $\overline{\text{COENB}}$  is LOW, the outputs are enabled. When  $\overline{\text{COENB}}$  is HIGH, the outputs are placed in a high-impedance state.

*DCM1-0 — Decimation Control*

The DCM1-0 inputs select the number of decimation registers to use (Table 1). Coefficients are passed from one cell to another at a rate determined by DCM1-0. When no decimation registers are selected, the coefficients are passed from cell to cell on every rising edge of CLK (no decimation). When one decimation register is selected, the coefficients are passed from cell to cell on every other rising edge of CLK (2:1 decimation). When two decimation registers are selected, the coefficients are passed from cell to cell on every third rising edge of CLK (3:1 decimation) and so on. DCM1-0 is latched and delayed internally.

*ADR2-0 — Cell Accumulator Select*

The ADR2-0 inputs select which cell's accumulator will be available at the SUM25-0 output or added to the output stage accumulator. In both cases, ADR2-0 is latched and delayed by one clock cycle. If the same address remains on the ADR2-0 inputs for more than one clock cycle, SUM25-0 will not change if the contents of the accumulator changes. Only the result from the first selection of the cell (first clock cycle) by ADR2-0 will be available. ADR2-0 is also used to select which accumulator to clear when ERASE is LOW.

*$\overline{\text{SENBH}}$  — MSB Output Enable*

When  $\overline{\text{SENBH}}$  is LOW, SUM25-16 is enabled. When  $\overline{\text{SENBH}}$  is HIGH, SUM25-16 is placed in a high-impedance state.

*$\overline{\text{SENBL}}$  — LSB Output Enable*

When  $\overline{\text{SENBL}}$  is LOW, SUM15-0 is enabled. When  $\overline{\text{SENBL}}$  is HIGH, SUM15-0 is placed in a high-impedance state.

*$\overline{\text{RESET}}$  — Register Reset Control*

When  $\overline{\text{RESET}}$  is LOW, all registers are cleared simultaneously except the cell accumulators.  $\overline{\text{RESET}}$  can be used with ERASE to clear all cell accumulators.  $\overline{\text{RESET}}$  is latched and delayed internally. Refer to Table 2.

*$\overline{\text{ERASE}}$  — Accumulator Erase Control*

When  $\overline{\text{ERASE}}$  is LOW, the cell accumulator specified by ADR2-0 is cleared. When  $\overline{\text{RESET}}$  is LOW in conjunction with ERASE, all cell accumulators are cleared. Refer to Table 2.

**MAXIMUM RATINGS** *Above which useful life may be impaired (Notes 1, 2, 3, 8)*

Storage temperature .....	-65°C to +150°C
Operating ambient temperature .....	-55°C to +125°C
V <sub>CC</sub> supply voltage with respect to ground .....	-0.5 V to +7.0 V
Input signal with respect to ground .....	-0.5 V to V <sub>CC</sub> + 0.5 V
Signal applied to high impedance output .....	-0.5 V to V <sub>CC</sub> + 0.5 V
Output current into low outputs .....	25 mA
Latchup current .....	> 400 mA

**OPERATING CONDITIONS** *To meet specified electrical and switching characteristics*

Mode	Temperature Range (Ambient)	Supply Voltage
Active Operation, Commercial	0°C to +70°C	4.75 V ≤ V <sub>CC</sub> ≤ 5.25 V
Active Operation, Military	-55°C to +125°C	4.50 V ≤ V <sub>CC</sub> ≤ 5.50 V

**ELECTRICAL CHARACTERISTICS** *Over Operating Conditions (Note 4)*

Symbol	Parameter	Test Condition	Min	Typ	Max	Unit
V <sub>OH</sub>	Output High Voltage	V <sub>CC</sub> = Min., I <sub>OH</sub> = -400 μA	2.6			V
V <sub>OL</sub>	Output Low Voltage	V <sub>CC</sub> = Min., I <sub>OL</sub> = 2.0 mA			0.4	V
V <sub>IH</sub>	Input High Voltage		2.0		V <sub>CC</sub>	V
V <sub>IL</sub>	Input Low Voltage	(Note 3)	0.0		0.8	V
I <sub>Ix</sub>	Input Current	Ground ≤ V <sub>IN</sub> ≤ V <sub>CC</sub> (Note 12)			±10	μA
I <sub>OZ</sub>	Output Leakage Current	(Note 12)			±10	μA
I <sub>CC1</sub>	V <sub>CC</sub> Current, Dynamic	(Notes 5, 6)			160	mA
I <sub>CC2</sub>	V <sub>CC</sub> Current, Quiescent	(Note 7)			750	μA
C <sub>IN</sub>	Input Capacitance	T <sub>A</sub> = 25°C, f = 1 MHz			10	pF
C <sub>OUT</sub>	Output Capacitance	T <sub>A</sub> = 25°C, f = 1 MHz			10	pF

## SWITCHING CHARACTERISTICS

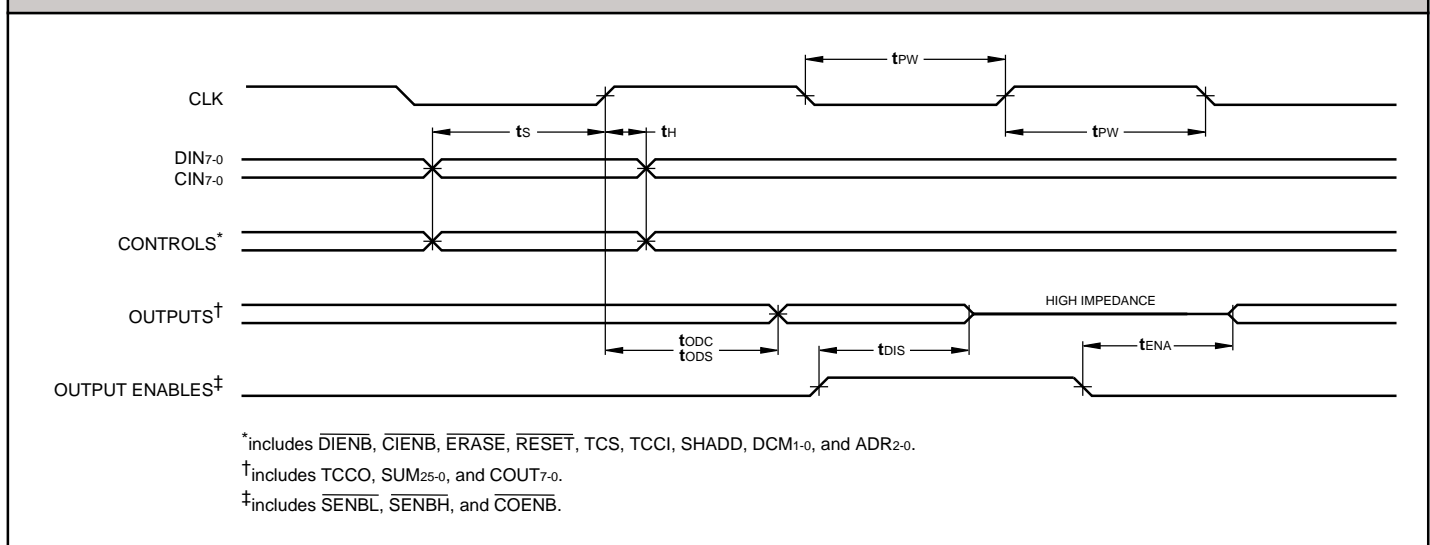
### COMMERCIAL OPERATING RANGE (0°C to +70°C) Notes 9, 10 (ns)

Symbol	Parameter	LF43881-							
		50*		40		33*		25*	
		Min	Max	Min	Max	Min	Max	Min	Max
t <sub>CYC</sub>	Cycle Time	50		39		33		25	
t <sub>PW</sub>	Clock Pulse Width	20		16		13		10	
t <sub>S</sub>	Input Setup Time	16		14		13		10	
t <sub>H</sub>	Input Hold Time	0		0		0		0	
t <sub>ODC</sub>	Coefficient Output Delay		24		20		18		16
t <sub>ODS</sub>	Sum Output Delay		27		25		21		18
t <sub>ENA</sub>	Three-State Output Enable Delay (Note 11)		20		15		15		12
t <sub>DIS</sub>	Three-State Output Disable Delay (Note 11)		20		15		15		12

### MILITARY OPERATING RANGE (-55°C to +125°C) Notes 9, 10 (ns)

Symbol	Parameter	LF43881-					
		50*		40*		33*	
		Min	Max	Min	Max	Min	Max
t <sub>CYC</sub>	Cycle Time	50		39		33	
t <sub>PW</sub>	Clock Pulse Width	20		16		13	
t <sub>S</sub>	Input Setup Time	20		17		13	
t <sub>H</sub>	Input Hold Time	0		0		0	
t <sub>ODC</sub>	Coefficient Output Delay		24		20		18
t <sub>ODS</sub>	Sum Output Delay		31		25		21
t <sub>ENA</sub>	Three-State Output Enable Delay (Note 11)		20		15		15
t <sub>DIS</sub>	Three-State Output Disable Delay (Note 11)		20		15		15

## SWITCHING WAVEFORMS



**\*DISCONTINUED SPEED GRADE**



**NOTES**

1. Maximum Ratings indicate stress specifications only. Functional operation of these products at values beyond those indicated in the Operating Conditions table is not implied. Exposure to maximum rating conditions for extended periods may affect reliability.

2. The products described by this specification include internal circuitry designed to protect the chip from damaging substrate injection currents and accumulations of static charge. Nevertheless, conventional precautions should be observed during storage, handling, and use of these circuits in order to avoid exposure to excessive electrical stress values.

3. This device provides hard clamping of transient undershoot and overshoot. Input levels below ground or above VCC will be clamped beginning at -0.6 V and VCC + 0.6 V. The device can withstand indefinite operation with inputs in the range of -0.5 V to +7.0 V. Device operation will not be adversely affected, however, input current levels will be well in excess of 100 mA.

4. Actual test conditions may vary from those designated but operation is guaranteed as specified.

5. Supply current for a given application can be accurately approximated by:

$$\frac{NCV^2F}{4}$$

where

- N = total number of device outputs
- C = capacitive load per output
- V = supply voltage
- F = clock frequency

6. Tested with all outputs changing every cycle and no load, at a 20 MHz clock rate.

7. Tested with all inputs within 0.1 V of VCC or Ground, no load.

8. These parameters are guaranteed but not 100% tested.

9. AC specifications are tested with input transition times less than 3 ns, output reference levels of 1.5 V (except tDIS test), and input levels of nominally 0 to 3.0 V. Output loading may be a resistive divider which provides for specified IOH and IOL at an output voltage of VOH min and VOL max respectively. Alternatively, a diode bridge with upper and lower current sources of IOH and IOL respectively, and a balancing voltage of 1.5 V may be used. Parasitic capacitance is 30 pF minimum, and may be distributed.

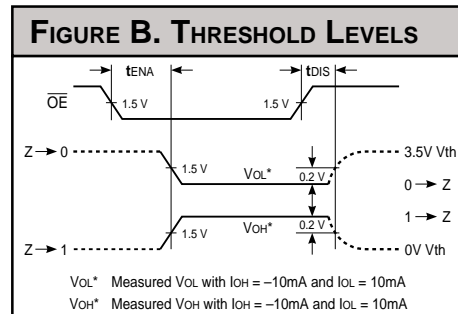
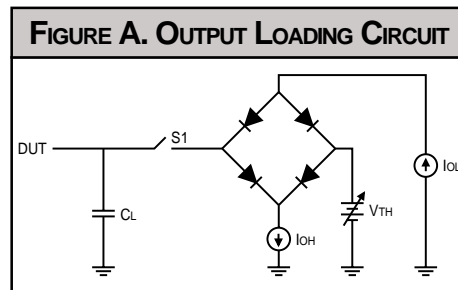
This device has high-speed outputs capable of large instantaneous current pulses and fast turn-on/turn-off times. As a result, care must be exercised in the testing of this device. The following measures are recommended:

- a. A 0.1 μF ceramic capacitor should be installed between VCC and Ground leads as close to the Device Under Test (DUT) as possible. Similar capacitors should be installed between device VCC and the tester common, and device ground and tester common.
- b. Ground and VCC supply planes must be brought directly to the DUT socket or contactor fingers.
- c. Input voltages should be adjusted to compensate for inductive ground and VCC noise to maintain required DUT input levels relative to the DUT ground pin.

10. Each parameter is shown as a minimum or maximum value. Input requirements are specified from the point of view of the external system driving the chip. Setup time, for example, is specified as a minimum since the external system must supply at least that much time to meet the worst-case requirements of all parts. Responses from the internal circuitry are specified from the point of view of the device. Output delay, for example, is specified as a maximum since worst-case operation of any device always provides data within that time.

11. For the tENA test, the transition is measured to the 1.5 V crossing point with datasheet loads. For the tDIS test, the transition is measured to the ±200mV level from the measured steady-state output voltage with ±10mA loads. The balancing voltage, VTH, is set at 3.5 V for Z-to-0 and 0-to-Z tests, and set at 0 V for Z-to-1 and 1-to-Z tests.

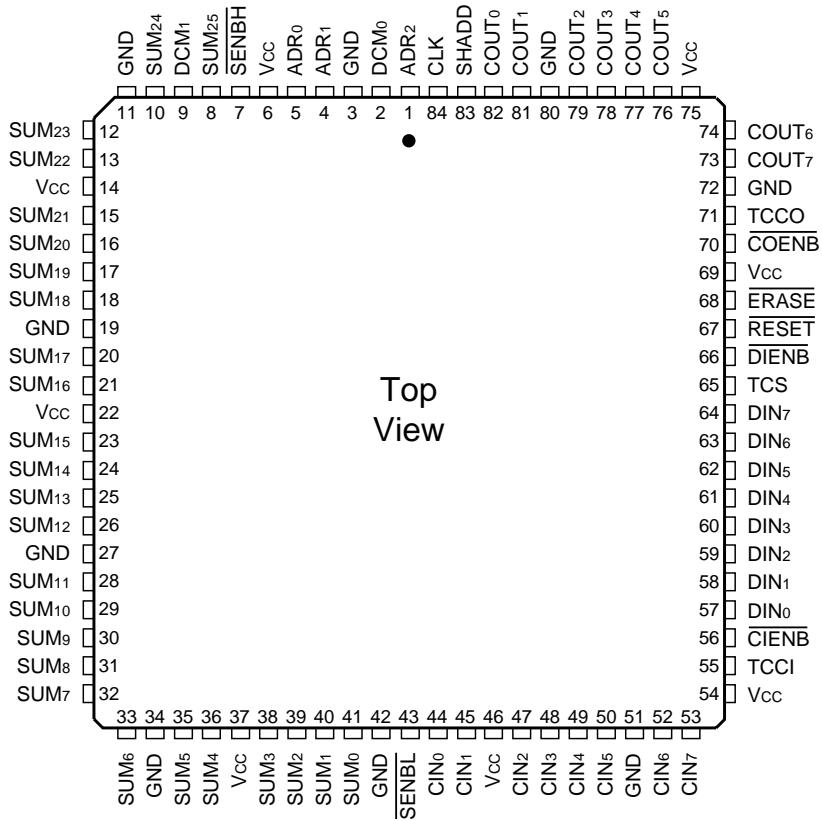
12. These parameters are only tested at the high temperature extreme, which is the worst case for leakage current.





**ORDERING INFORMATION**

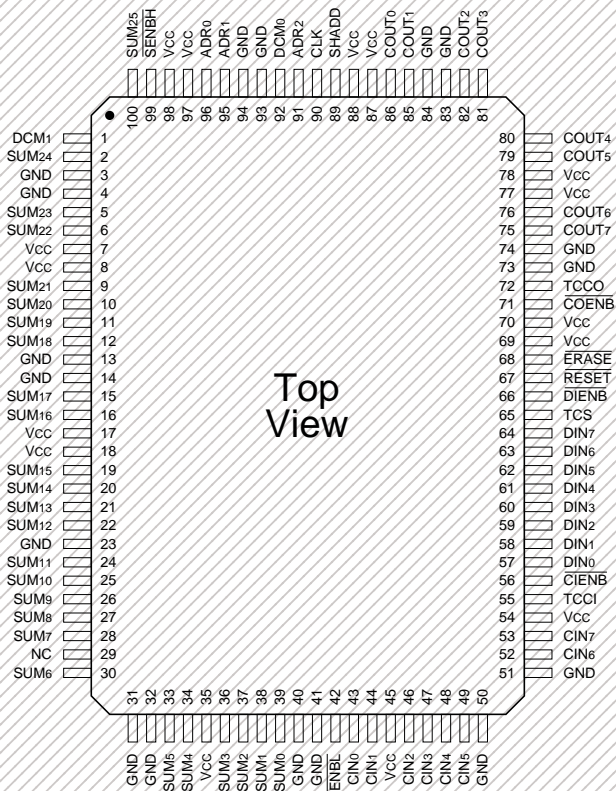
**84-pin**



Speed	<b>Plastic J-Lead Chip Carrier (J3)</b>
	<b>0°C to +70°C — COMMERCIAL SCREENING</b>
40 ns	LF43881JC40

#### ORDERING INFORMATION

100-pin

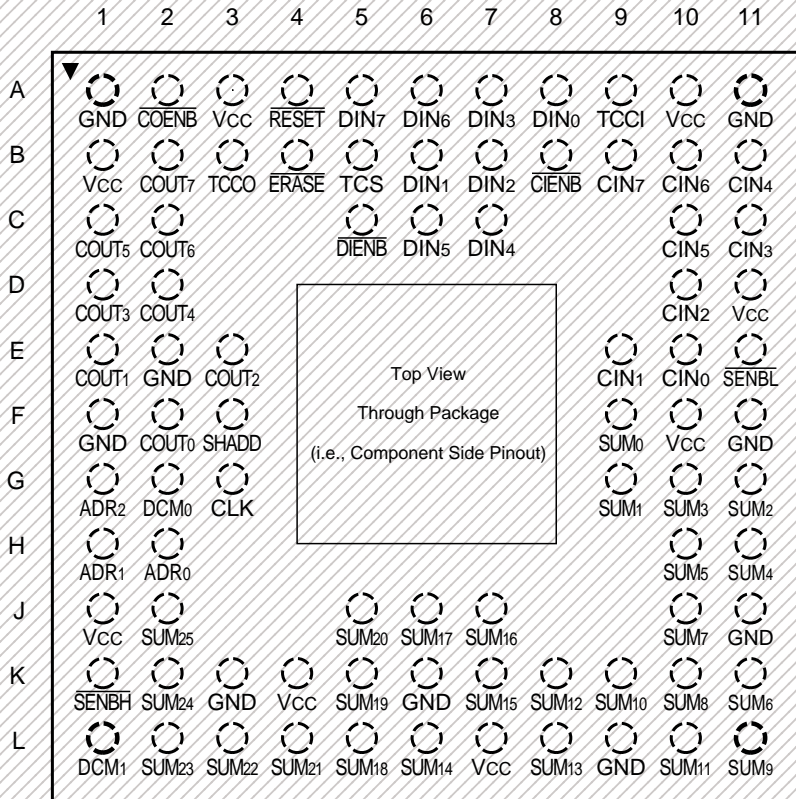


Discontinued Package

<b>Speed</b>	<b>Plastic Quad Flatpack (Q2)</b>
	<b>0°C to +70°C — COMMERCIAL SCREENING</b>

**ORDERING INFORMATION**

84-pin



**Discontinued Package**

Speed	Ceramic Pin Grid Array (G3)
	0°C to +70°C — COMMERCIAL SCREENING
	-55°C to +125°C — COMMERCIAL SCREENING
	-55°C to +125°C — MIL-STD-883 COMPLIANT