FEATURES

- Three-State, 4-Bit, Cascadable, Parallel-In, Parallel-Out Registers
- Schottky-Diode-Clamped Transistors
- Low Power Dissipation . . . 75mW Typical (Enabled)
- Applications: N-Bit Serial-To-Parallel Converter
 N-Bit Parallel-To-Serial Converter
 N-Bit Storage Register
- Pin for pin compatible with LS395

DESCRIPTION

These 4-bit registers feature parallel inputs, parallel outputs, and clock, serial, load/shift, output control and direct overriding clear inputs.

Shifting is accomplished when the load/shift control is low. Parallel loading is accomplished by applying the four bits of data and taking the load/shift control input high. The data is loaded into the associated flip-flops and appears at the outputs after the high-to-low transition of the clock input. During parallel loading, the entry of serial data is inhibited.

When the output control is low, the normal logic levels of the four outputs are available for driving the loads or bus lines. The outputs are disabled independently from the level of the clock by a high logic level at the output control input. The outputs then present a high impedance and neither load nor drive the bus line; however, sequential operation of the reigsters is not affected. During the high-impedance mode, the output at $Q_{D^{\prime}}$ is still available for cascading.

The 9LS/54LS395A is characterized for operation over the full military temperature range of -55°C to 125°C ; the 9LS/74LS395A is characterized for operation from 0°C to 70°C .

LS395A OUTPUTS VCC QA QB QC QD QD' CK TIGHING GENERAL LOAD OND SERIAL LOAD

FUNCTION TABLE

| | 3.5 | TATE | CASCADE | | | | | | |
|-------|-----------------------|----------|---------|---------------------|-----------------|----------------------|----------------|---------------|--------------------------|
| CLEAR | LOAD/SHIFT CONTROL | СГОСК | SERIAL | PARALLEL A B C D | QA | σB | o _C | QD | 0UТРUТ Q _D |
| L | x | х | х | xxxx | L | L | L | L | L |
| н | н | н | х | xxxx | Q _{A0} | Q_{B0} | a_{co} | αDO | Q _{D0} |
| н | Н | + | х | abcd | а | b | c | d | d |
| н | L | н | × | x x x x | α_{A0} | α_{B0} | σ_{C0} | σ_{D0} | a_{D0} |
| н | L | 1 | н | x x x x | н | \mathbf{Q}_{An} | Q_{Bn} | QCn | QCn |
| н | L | ŧ | L | xxxx | L | σ_{An} | σ_{Bn} | QCn | Q _{Cn} |

When the output control is high, the 3-state outputs are disabled to the high-impedance state; however, sequential operation of the registers and the output at \mathbf{Q}_{D} are not affected.

QAn, QBn, QCn, QDn = the level of QA, QB, QC, or QD, respectively, before the most recent 1 transition of the clock.



H = high level (steady state), L = low level (steady state), X = irrelevant (any input, including transitions)

^{↓ =} transition from high to low level.

 $Q_{A0}, Q_{B0}, Q_{C0}, Q_{D0}$ = the level of $Q_A, Q_B, Q_C,$ or $Q_D,$ respectively, before the indicated steady state input conditions were established.

Recommended Operating Conditions

| econnienced operating continues | (| 9LS/54LS | | 9LS/74LS | | | Unit |
|--|-------------|--------------|-----|----------|--------------|----------|-------|
| | Min | Nom | Max | Min | Nom | Max | Oiiii |
| Construction V- | 4.5 | 5 | 5.5 | 4.75 | 5 | 5.25 | V |
| Supply voltage, V _{CC} | | | -1 | | | -2.6 | mΑ |
| High-level output current, IOH | | | 4 | | T | 8 | mΑ |
| Low-level output current, IOL | | | | 2 | | 25 | MHz |
| Clock frequency, f _{clock} | 0 | <u> </u> | 25 | Ô | | 25 | |
| Width of clock pulse, tw(clock) | 25 | <u> </u> | | 25 | |] | ns |
| Setup time, high-level or low-level data, t _{setup} | 20 | | | 20 | L | <u> </u> | ns |
| Hold time, high-level or low-level data, thold | 10 | <u> </u> | | 10 | ļ | ļ | ns |
| Operating free-air temperature, T _A | -55 | | 125 | 0 | <u> </u> | 70 | °c |

Electrical Characteristics Over Recommended Free-Air Temperature Range (Unless Otherwise Noted)

| | | 1 : | 9LS/54LS | . | | 3 | Unit | | | |
|-----------------|-----------------------|---------------------------------|---------------------------------|--|--|------|--------------|----------|-------|-----|
| Parameter | Test Conditions* | | | | Typ** | Max | | Min | Тур** | Max |
| · | | | 2 | + | | 2 | | | V | |
| ViH | | | | | | 0.7 | | | 0.8 | V |
| VIL | 34 -84151 | L= 18mA | | +- | | -1.5 | | | -1.5 | V |
| ν _I | V _{CC} =MIN, | | | + | + | | | 124 | | v |
| V _{OH} | AIT=AITwax | | | 2.4 | 3.4 | | 2.4 | 3.1 | | L v |
| | V _{CC} =MIN | Q _A , Q _B | IOL=12mA | | 0.25 | 0.4 | | 0.25 | 0.40 | V |
| | VIL=VIL max, | | I _{OC} =24mA | | | | | 0.35 | 0.50 | |
| V _{OL} | V _{1H} =2V | Q _D | I _{OL} =4mA | | 0.25 | 0.4 | | 0.25 | 0.40 | V |
| | | | I _{OL} =8mA | | 1 | | | 0.35 | 0.50 | |
| | V _{CC} =MAX, | VIH=2V, | QA, QB | | | 20 | | | 20 | μΔ |
| OZH | V _O =2.7V | | α _C , α _D | | | | | ļ | | ļ |
| | V _{CC} =MAX, | V _{IH} =2V, | Q _A , Q _B | | | -20 | | | -20 | μ٨ |
| IOZL | V _O =0.4V | | Q _C , Q _D | | | ļ | | <u> </u> | | - |
| t _i | V _{CC} =MAX, | V ₁ =7V | | | | 0.1 | | | 0.1 | m, |
| hн | V _{CC} =MAX, | V _I =2.7V | | | | 20 | | <u> </u> | 20 | μ, |
| IIL. | V _{CC} =MAX, | V ₁ =0.4V | | | | -0.4 | ļ | | -0.4 | m. |
| los† | V _{CC} =MAX | | | -15 | | -100 | -15 | | -100 | m. |
| .03. | | | Condition A | | 18 | 29 | | 18 | 29 | m. |
| Icc†† | V _{CC} =MAX, | | Condition B | | 15 | 25 | | 15 | 25 | L |

^{*}For conditions shown as MIN or MAX, use the appropriate value specified under recommended operating conditions for the applicable



^{**}All typical values are at V_{CC} = 5V, T_A = 25°C.

[†]Not more than one output should be shorted at a time.

^{††}ICC is measured with the outputs open, the serial input and mode control at 4.5V, and the data inputs grounded under the following conditions:

A. Output control at 4.5V and a momentary 3V, then ground, applied to clock input.

B. Output control and clock input grounded.

Switching Characteristics, $V_{cc} = 5V$ Over Recommended Free-Air Temperature Range

| Parameters | −55°C | | | +25°C | | | +125°C | | | | |
|---------------------------------|---------|----------------------|---------|---------|---------|------|---------|-----|-----|------|--|
| raiameteis | Min | Тур | Max | Min | Тур | Max | Min | Тур | Max | Unit | |
| Test Conditions: C _L | = 15pF | R _L = 2 | kΩ (See | Fig. C, | page 2- | 174) | | | | | |
| f _{max} | | | | 25 | 35 | | | | | MHz | |
| Clear to tPHL output | | 27 | 40 | | 23 | 35 | | 27 | 40 | ns | |
| ^t PLH | | 27 | 40 | | 23 | 35 | | 27 | 40 | ns | |
| ^t PHL | | 24 | 35 | | 20 | 30 | | 24 | 35 | ns | |
| ^t PZH | | 17 | 25 | | 13 | 20 | | 17 | 25 | ns | |
| [†] PZL | | 28 | 41 | | 24 | 36 | | 28 | 41 | п\$ | |
| ^t PHZ | | 15 | 22 | | 11 | 17 | | 15 | 22 | ns | |
| ^t PLZ | | 19 | 27 | | 15 | 23 | | 19 | 27 | ns | |
| Test Conditions: C _L | = 5.0pF | , R _L = 2 | kΩ (See | Fig. C, | page 2 | 174) | | | | | |
| tHZ | | 13 | 22 | | 11 | 17 | | 13 | 22 | ns | |
| ^t LZ | | 18 | 27 | | 15 | 23 | | 18 | 27 | ns | |
| Test Conditions: C _L | = 50pF, | R _L = 2 | kΩ (See | Fig. C, | page 2- | 174) | <u></u> | | | | |
| ^t PHL | | 30 | 44 | | 26 | 39 | | 30 | 44 | ns | |
| tPLH | | 30 | 44 | | 26 | . 39 | | 30 | 44 | ns | |
| tphL | | 27 | 38 | | 23 | 34 | | 27 | 38 | ns | |
| ^t PZH | | 20 | 29 | | 18 | 24 | | 22 | 27 | ns | |
| ^t PZL | | 31 | 45 | | 27 | 40 | | 30 | 45 | ns | |
| ^t PHZ | | 18 | 26 | | 14 | 20 | | 19 | 26 | ns | |
| ^t PLZ | | 22 | 32 | | 18 | 27 | | 22 | 32 | ns | |

Note: AC specification shown under -55° C and $+125^{\circ}$ C are for 9LS devices only. All 50pF specifications are for 9LS devices only.

LOGIC DIAGRAM



